

## A Connectionist Account of Asymmetric Category Learning in Early Infancy

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Young infants show unexplained asymmetries in the exclusivity of categories formed on the basis of visually presented stimuli. A connectionist model is described that shows similar exclusivity asymmetries when categorizing the same stimuli presented to infants. The asymmetries can be explained in terms of an associative learning mechanism, distributed internal representations, and the statistics of the feature distributions in the stimuli. The model was used to explore the robustness of this asymmetry. The model predicts that the asymmetry will persist when a category is acquired in the presence of mixed category exemplars. An experiment with 3–4-month-olds showed that asymmetric exclusivity persisted in the presence of mixed-exemplar familiarization, thereby confirming the model's prediction.

Young infants can form perceptual category representations when presented with a set of perceptually similar stimuli from the same class. These representations allow infants to organize their perceptual experiences into groupings that in many instances come to have conceptual significance for children and adults. For example, by 3 or 4 months of age infants have been shown to categorize a range of real-world images of cats, dogs, horses, chairs, and couches (Madole & Oakes, 1999; Quinn, 1998; Quinn & Eimas, 1996a). However, the perceptual category representations do not always have the same characteristics as might be expected from the corresponding adult category representations. In particular, the extension and exclusivity of the perceptual category representations of infants (i.e., the range of exemplars accepted or rejected as members of the category) may differ from those of adult category representations.

Quinn, Eimas, and Rosenkrantz (1993) used a familiarization–novelty preference technique to determine if the perceptual cate-

gory representations of familiar animals (e.g., cats and dogs) acquired by young infants would exclude perceptually similar exemplars from contrasting basic-level categories. They found that when 3–4-month-olds were familiarized with six pairs of cat photographs presented sequentially (12 photographs), the infants subsequently preferred to look at a novel dog photograph rather than a novel cat photograph. Because infants have an inherent preference for looking at unfamiliar stimuli (Fagan, 1970; Fantz, 1964; Slater, 1995), this result was interpreted as showing that the infants had developed a category representation of Cat that included novel cats (hence less looking at the cat photograph) but excluded novel dogs (hence more looking at the dog photograph). However, when the infants were initially familiarized with six pairs of dog photographs sequentially (12 photographs), they showed no subsequent preference for looking at either a novel dog or a novel cat. Furthermore, control conditions revealed that (a) the infants preferred to look at a novel test bird after initial familiarization with either dogs or cats, (b) there was no a priori preference for dogs over cats, and (c) the infants were able to discriminate within the Cat and Dog categories. Taken together, these findings led Quinn et al. to suggest that the 3–4-month-olds had formed a perceptual category representation of Dog that included novel dogs but also included novel cats.

There appears to be an asymmetry in the exclusivity of the two perceptual category representations formed during familiarization. The Cat representation excludes novel dogs, whereas the Dog representation does not exclude novel cats. The reason for this asymmetry remains unclear, although Quinn et al. (1993) presented some evidence that it might be related to greater variability among dogs. We believe that a full explanation of this asymmetry requires a mechanistic account of how categories are formed by infants during a test session. Some researchers have tried to identify what information within a set of stimuli might be used by infants to delimit a perceptual category representation (Quinn &

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This work was supported in part by a collaborative research grant awarded by the British Council and the Belgian Commissariat Général aux Relations Internationales Belges, by Belgian Interuniversity Attraction Poles Grant P4/19, and by Grant BCS-0096020 from the National Science Foundation.

We are grateful to Les Cohen, Carolyn Rovee-Collier, and Tom Shultz for helpful comments on a draft of this article.

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Eimas, 1996b; Younger, 1985; Younger & Cohen, 1986). Although this approach can be very revealing about the basis for categorization, it leaves unanswered the question of how categories are causally derived from the set of exemplars experienced by the infant. Given that the role of developmental psychology is to establish the causal mechanisms by which behavior emerges, we propose in this article to explore how and why young infants categorize complex visual images in the way they do. To achieve this goal we present a combination of connectionist (computational) modeling and an experimental study of infant behaviors designed to test the legitimacy of the modeling.

Computational modeling provides a tool for exploring the mechanisms that underlie behavior. *Connectionist models* are computer models loosely based on the principles of neural information processing (Elman et al., 1996; Mareschal, in press; McLeod, Plunkett, & Rolls, 1998; Rumelhart & McClelland, 1986). They are not intended to be neural models. Instead, they attempt to strike a balance between importing some of the basic concepts from the neurosciences and formulating questions about behavior in terms of high-level cognitive concepts.

From a developmental perspective, connectionist networks are ideal for modeling because they develop their own internal representations as a result of interacting with a structured environment (Mareschal & Shultz, 1996; Plunkett & Sinha, 1992). Although connectionist modeling has its roots in associationist learning paradigms, it has inherited the Hebbian rather than the Hullian tradition. That is, what goes on inside the network (i.e., the internal representation of information) is as important in determining the overall behavior of the network as are the correlations between the inputs (stimuli) and the outputs (responses).

### Building a Model of Infant Categorization

Many infant visual categorization tasks rely on preferential looking techniques that are based on the finding that infants direct attention more to unfamiliar or unexpected stimuli (Fagan, 1970; Fantz, 1964; Slater, 1995). The standard interpretation of this

behavior is that the infants are comparing an input stimulus to an internal representation of the same stimulus (e.g., Charlesworth, 1969; Cohen, 1973; Sokolov, 1963). As long as there is a discrepancy between the information stored in the internal representation and the visual input, the infant continues to attend to the stimulus. While attending to the stimulus, the infant updates his or her internal representation. When the information in the internal representation is no longer discrepant with respect to the visual input, attention is switched elsewhere. When a familiar object is presented, there is little or no attending because the infant already has a reliable internal representation of that object. In contrast, when an unfamiliar or unexpected object is presented, there is much attending because an internal representation has to be constructed or adjusted. The degree to which the novel object differs from the information stored in the existing internal representations determines the amount of adjusting that has to be done and hence the duration of attention.

We used a connectionist autoencoder to model the relation between attention and representation construction (Mareschal & French, 1997, 2000; Schafer & Mareschal, in press; see Figure 1). An autoencoder is a feedforward connectionist network with a single layer of hidden units (Ackley, Hinton, & Sejnowski, 1985; Rumelhart & McClelland, 1986). The network learns to reproduce on the output units the pattern of activation across the input units. The number of hidden units must be smaller than the number of input or output units. This architectural constraint produces a bottleneck in the flow of information through the network. Learning in an autoencoder consists of developing a more compact internal representation of the input (at the hidden-unit level) that is sufficiently reliable to reproduce all of the information in the original input—hence the incentive to develop category-based representations. Information is first compressed into an internal representation and then expanded to reproduce the original input. The successive cycles of training in the autoencoder constitute an iterative process by which a reliable internal representation of the input is developed. The reliability of the representation is tested by

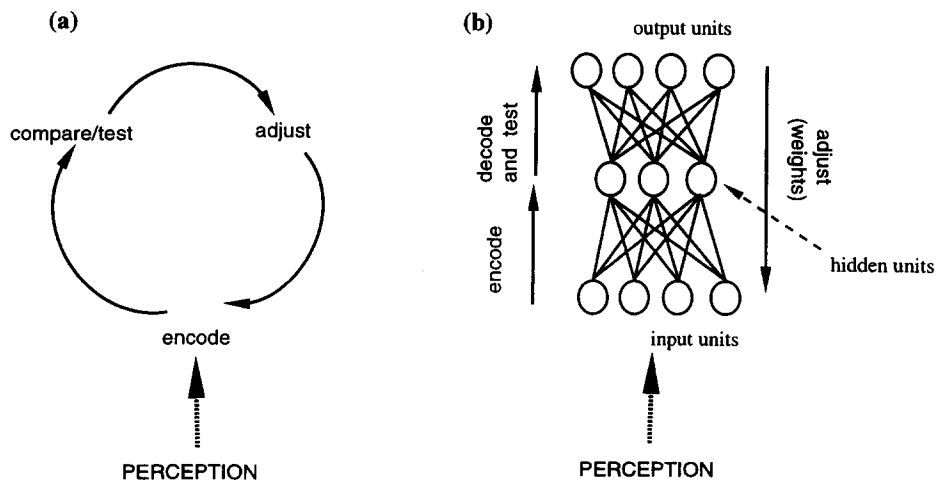


Figure 1. Learning via iterative representation adjustment in (a) infants and (b) connectionist autoencoder networks. From "Mechanisms of Categorization in Infancy," by D. Mareschal and R. M. French, 2000, *Infancy*, 1, p. 62. Copyright 2000 by Lawrence Erlbaum Associates, Inc. Reprinted with permission.

expanding it and comparing the resulting predictions with the actual stimulus being encoded. Similar networks have been used to produce compressed representations of video images (Cottrell, Munro, & Zipser, 1988).

We suggest that during the period of captured attention, infants are actively involved in an iterative process of encoding visual input into an internal representation and then assessing that representation against continuing perceptual input. This assessment is accomplished by using the internal representation to predict what the properties of the stimulus are. As long as the representation fails to predict the stimulus properties, the infant continues to fixate the stimulus and to update the internal representation. Similar interpretations have been suggested elsewhere (Mareschal & French, 2000; Mareschal, Plunkett, & Harris, 1999; Munakata, McClelland, Johnson, & Siegler, 1997; see also Di Lollo, Enns, & Rensink, in press, for a comparable account of adult visual object recognition).

This modeling approach has several implications. It suggests that infant looking times are positively correlated with network error.<sup>1</sup> The greater the error, the longer the looking time. Stimuli presented for a very short time will be encoded less well and produce more error than stimuli presented for a longer period. However, prolonged exposure after error (attention) has fallen off will not improve memory of the stimulus. The degree to which error (looking time) increases on presentation of a novel object depends on the similarity between the novel object and the familiar object. Presenting a series of similar objects from the same perceptual category leads to a progressive error drop on future similar objects. A prototype of the set of objects leads to lower error than do individual objects. All of this is true both of autoencoders (where output error is the measurable quantity) and of infants (where looking time is the measurable quantity).

### Simulation 1: The Development of Cat and Dog Categories

The modeling results in this section and the next simulation section are based on the performance of a standard 10-8-10 feed-forward backpropagation network.<sup>2</sup> Autoencoders are reasonably robust in response to variations in the number of hidden units and the value of specific parameters. One requirement for efficient autoencoding is that there be a sufficient number of hidden units to capture the principal components of variation in the data. However, too many hidden units may reduce the network's ability to generalize to novel exemplars. These and other aspects of autoencoding are discussed in Hertz, Krogh, and Palmer (1991).

To model the original exclusivity asymmetry effect, we obtained data for training the networks from measurements of the original cat and dog pictures used by Quinn et al. (1993). These data are tabulated in the Appendix. There were 18 dogs and 18 cats classified according to the following 10 traits: head length, head width, eye separation, ear separation, ear length, nose length, nose width, leg length, vertical extent, and horizontal extent. Although it is difficult to say for certain which of these features the infants used during categorization, it is well known that infants can segregate items into categories on the basis of attributes with different values (Younger, 1985; see Quinn & Johnson, 1997, for a detailed justification of similar input features). The feature values

were normalized<sup>3</sup> to be between 0 and 1. The input data are discussed in more detail below.

Twelve items from one category were presented sequentially to the network in groups of two (i.e., weights were updated in batches of two) to capture the fact that pairs of pictures were presented to the infants during the familiarization trials. Networks were trained for 250 epochs (weight updates) on one pair of patterns before being presented with the next pair. We did this to reflect the fact that in the Quinn and Eimas studies (Eimas, Quinn, & Cowan, 1994; Quinn & Eimas, 1996a; Quinn et al., 1993) infants were shown pairs of pictures for a fixed duration of time. The total amount of training was therefore  $6 \times 250 = 1,500$  weight updates. The results are averaged over 50 network replications, each with random initial weights. The remaining six items from each category were used to test whether the networks had formed category representations.

Like infants, these networks form both Cat and Dog categories. Figure 2 shows the initial error score (i.e., the *sum squared error* between the actual output produced and the ideal target value, measured across all output units), the error score after 12 presentations of either cats or dogs, and the average error score (after training) for the six remaining exemplars in either the Cat or Dog category. After learning, error is lower, which suggests that the network has developed reliable internal representations of cats or dogs. The generalization error rises slightly, showing that the networks recognize these exemplars as novel. Infants are also able to distinguish individual exemplars within the category (Quinn et al., 1993). However, the generalization error remains well below the initial error, which suggests that the new exemplars are assimilated within the category representation formed by the networks across the hidden units.

### *The Asymmetric Exclusivity of the Cat and Dog Categories*

Quinn et al. (1993) found that there was an asymmetry in the exclusivity of the Cat and Dog categories developed by infants. Figure 3 shows what happens when networks trained on cats are presented with a novel cat and a novel dog and when networks trained on dogs are tested with a novel dog and a novel cat. In these network models (as with infants), the acquisition of categorical representations is inferred from their differential sum-squared-error responses (preferential looking responses) when presented with a novel exemplar of the familiar category and when presented with a novel exemplar of the novel category. The differences in

<sup>1</sup> This is a common way of relating response times to network error scores (e.g., Mareschal et al., 1999; Quinn & Johnson, 1997; Seidenberg & McClelland, 1989; but see Bullinaria, 1995, for possible counterarguments).

<sup>2</sup> The parameter values were as follows: learning rate = .2, momentum = .9, and Fahlman offset = .1. A description of the role of learning-rate and momentum can be found in Plunkett and Elman (1997). The Fahlman offset is discussed in Fahlman (1988).

<sup>3</sup> This transformation preserves the covariation between cues, which is important because both infants (Younger, 1985) and autoencoder networks (Mareschal & French, 2000) have been shown to use covariation information in establishing category boundaries.

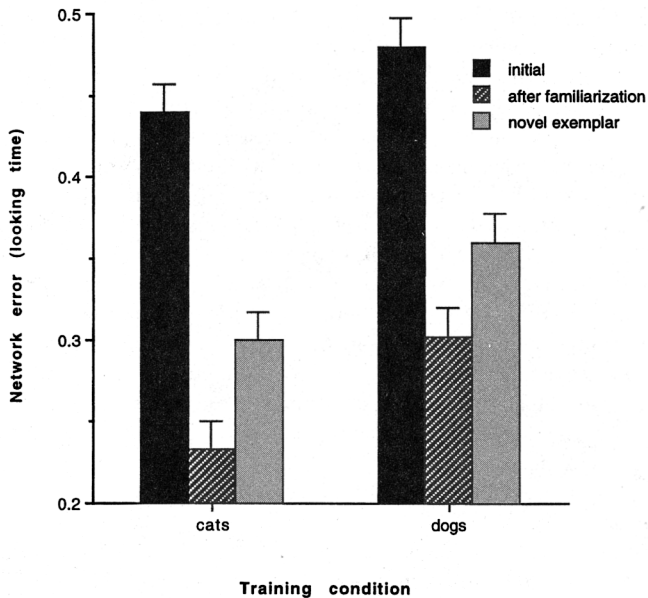


Figure 2. Mean error prior to familiarization, after familiarization, and on novel exemplars after familiarization for networks trained with cats or dogs.

these error scores reflect the differences in looking times toward each of the stimuli that are observed with infants.

When the networks are initially trained on cats, the presentation of a novel dog exemplar results in a large error score relative to that produced by the presentation of a novel cat exemplar; this corresponds to a longer looking time in the results observed with infants. Dogs are not included within the category representation of cats. In contrast, when the networks are initially trained on dogs, the presentation of a novel cat results in only a small increase in error relative to that produced by the presentation of a novel dog, which suggests that the cats have been included in the Dog category. Hence, the networks also show an asymmetry in the exclusivity of the category representations developed.

It could be argued that the asymmetry arises from the unequal learning of the Cat and Dog categories by the networks. It may take longer to learn the Dog category than the Cat category; hence, training for a fixed number of epochs would lead to a less established representation of Dog by the networks. To address this possibility, we trained 50 new networks as described above but with one exception. These networks were trained to a fixed error criterion rather than a fixed epoch criterion. Networks were trained on each pair of familiarization exemplars until all output units were within 0.2 of their target values.<sup>4</sup> This ensured that the networks learned to autoencode every input to the same minimum criterion. Under these conditions, networks familiarized with cats showed average errors of 0.26 ( $SD = 0.05$ ) and 0.45 ( $SD = 0.03$ ) when presented with a novel cat and a novel dog, respectively, whereas networks familiarized with dogs showed average errors of 0.35 ( $SD = 0.15$ ) and 0.41 ( $SD = 0.12$ ) when presented with a novel dog and a novel cat, respectively. Thus, the exclusivity asymmetry persisted even when networks were familiarized to a fixed error criterion.

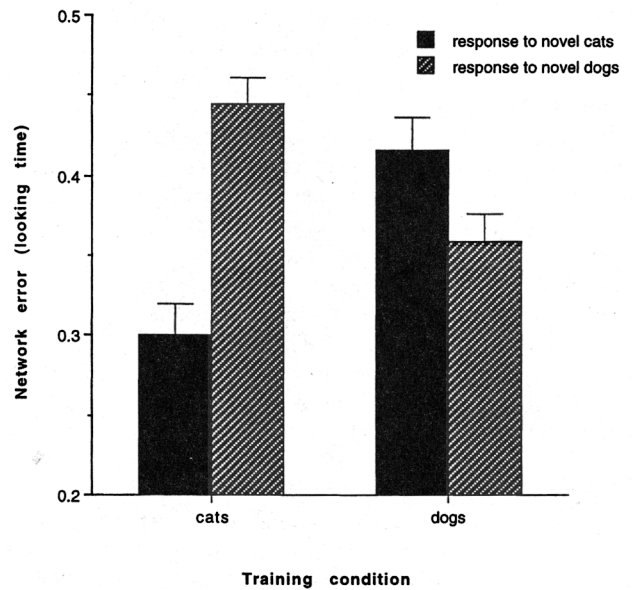


Figure 3. Mean error on a novel cat exemplar and a novel dog exemplar for networks trained on cats or dogs.

#### Distribution of Features in the Stimuli

The associative learning mechanisms embodied in connectionist networks (and described by the mathematics of these networks), when coupled with the nonlinear response of hidden units, provide a mechanistic account of *how* information is processed in such a system. However, a full explanation of the asymmetric exclusivity requires an account of *why* the system learns a representation for cats that excludes dogs but learns a representation for dogs that includes cats. Connectionist networks extract the correlations between features present in their learning environment. The distributional characteristics of the internal representations (developed across the hidden units) reflect the distributional characteristics of the corresponding categories in the environment, which suggests that an explanation for why the networks exhibit an exclusivity asymmetry may be found by examining the input data. Figure 4 shows the probability distributions of the 10 traits, for both cats and dogs, when fit to gaussian distributions using means and standard deviations derived from the normalized feature values.<sup>5</sup> Some of the traits are very similar in terms of their means and distributions for both cats and dogs (e.g., head length and head width). Others, especially nose length and nose width, are very different and will provide the crucial explanation for the unexpected looking asymmetries reported by Quinn et al. (1993).

Consider the single trait of nose width. The (normalized) mean nose width for the dog population is 0.53 with a standard deviation

<sup>4</sup> For practical reasons, a maximum criterion of 2,500 epochs (10 times the 250-epoch criterion) was used to terminate any simulations that failed to reach the 0.2 error criterion. This is analogous to the fact that, in practice, any study with infants has a fixed maximum duration.

<sup>5</sup> Although the fitted normal distributions may predict negative feature value (e.g., eye separation), the actual values used to train networks were always between 0 and 1. The negative predicted values reflect the presence of a skew in the underlying distribution of actual values.

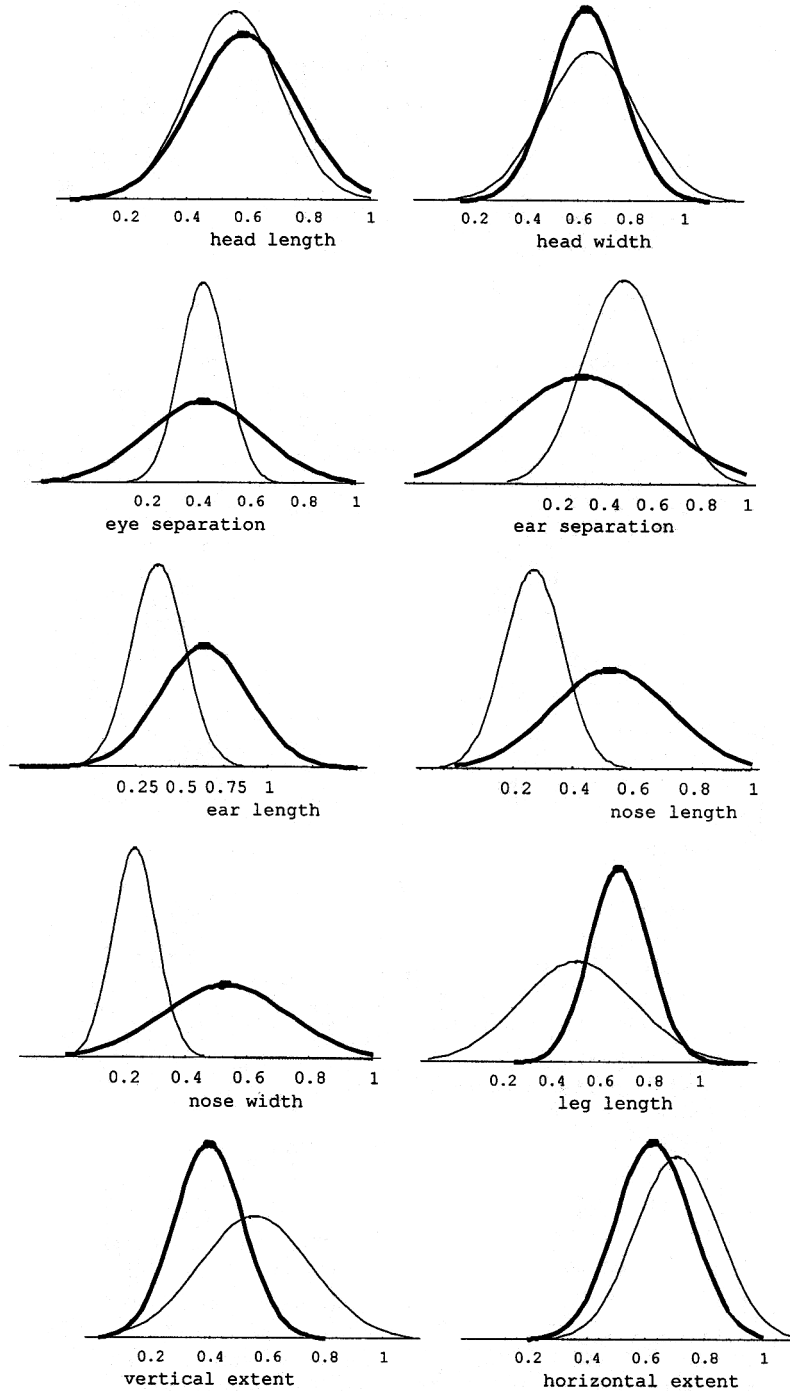


Figure 4. Gaussian probability distributions generated from the means and standard deviations of normalized cat features (thin lines) and dog features (thick lines). The area under each curve sums to 1.0.

of 0.20, whereas the mean for the cat population is 0.24 with a much smaller standard deviation of 0.07. Consequently, the nose width of virtually all cats in the population will fall within 2 *SD* of the nose-width mean for dogs. On the other hand, the nose width of the majority of dogs does not fall within 2 *SD* of the nose-width mean for cats. The result, in short, is that at least for this trait, all

cats could be exemplars of dogs, whereas most dogs could not be exemplars of cats.

When we examine all of the members of the two populations, we see that the values of all 10 traits for 9 (i.e., 50%) of the members of the Cat category fall within a 2-*SD* cutoff for those traits for the Dog category. Fully half of the cats in the population

could be reasonably classified as dogs. In contrast, the smaller means and lower variances of a number of traits (especially nose length and nose width) for cats compared with dogs means that only 2 of the 18 dogs (i.e., 11%) could conceivably be classified as members of the Cat category.

A corollary of this finding is that networks will, on average, generalize their autoencoding responses better in the dog-to-cat direction than in the cat-to-dog direction. When presented with a novel cat, a network trained on dogs will recognize this item as a member of the category it has learned (i.e., Dog) and for which it has also learned to output an appropriate feature description. In contrast, when presented with a novel dog, a network trained on cats will fail to recognize this item as a member of the category it has learned (i.e., Cat) and will be unable to output an appropriate feature description.

The exclusivity asymmetry of the categories formed on the basis of these exemplars reflects the distribution of features characteristic of the cat and dog exemplars presented to the networks (and infants). The key feature of the data is that the distribution of values for the Cat features are (in general) subsumed within the distribution of Dog features. There are two components to these distributional characteristics: (a) The Dog distributions are sometimes broader than the Cat distributions, and (b) the Cat values are often included within the range of Dog values. The greater range of Dog values is a necessary but not sufficient condition for the asymmetric exclusivity to appear. If, on the one hand, the Dog and Cat distributions had the same range, then there would be no exclusion in either direction. If, on the other hand, the Cat and Dog feature values had different ranges but no overlap, then there would be an exclusivity in both directions. To see this, suppose that the cats had feature values ranging on the interval  $[0, 0.25]$  and that the dogs had feature values ranging on the interval  $[0.5, 1.0]$ . Networks initially trained with cats would have no experience of processing clusters of values in the range  $[0.5, 1.0]$ . Thus, when presented with a novel dog input, they would mostly likely produce a default value of the mean of their experiences (0.125) or the maximum of their range (0.25) along each dimension. Either result would yield a large error observed in response to a novel dog input. Similarly, networks initially trained on dogs would have no experience of processing clusters of values in the range  $[0, 0.25]$ . When presented with a novel cat input, they would most likely produce a default value of the mean of their experiences (0.75) or the minimum of their range (0.5) along each dimension. Either outcome would result in a large error observed in response to a novel dog input. With no overlap in feature distributions, behavior consistent with symmetric exclusivity would be observed.

The degree to which the inclusion relationship observed in the nose-width feature holds across the set of features determines the degree to which an asymmetric exclusivity effect is observed. It is not just the greater variability of dogs along certain feature dimensions that causes the exclusivity asymmetry. The inclusion relationship with respect to cats also plays a crucial role.

However, the asymmetry inherent in the data is translated into corresponding behavior only because connectionist networks (and presumably infants) develop internal representations that reflect the distributions of the input features. Thus, the internal representation for Cat will be subsumed within the internal representation for Dog along several dimensions. It is because the internal rep-

resentations share this inclusion relationship that an asymmetry in error (looking time) is observed.

### Simulation 2: Learning From Mixed Exemplars

Categories are rarely acquired in isolation. In contrast to infants presented with cats or dogs in a series of laboratory familiarization trials, infants engaged in casual observation of their nursery environments presumably do not encounter numerous objects from the same natural kind or artifactual category presented in close temporal proximity. Infants would be more likely to encounter multiple objects from various categories in a quick scan of their immediate surroundings. The question that arises for researchers interested in the early development of categorization is how infant categorization performance will be affected when infants are presented with instances from two or more categories in the same familiarization session. It can be reasoned that experiencing two categories during learning will enhance the formation of distinct categories because examples of one category will provide a contrasting reference for learning the other category. Alternatively, it can be argued that presenting two categories simultaneously will create interference between them, thereby making the construction of a representation for each more difficult.

The evidence that is relevant to the contrast and interference hypotheses is mixed. For example, in studies of the acquisition of dot pattern categories, the category representations formed by both adults and young infants were enhanced in experimental sessions in which multiple categories were presented (Homa & Chambliss, 1975; Quinn, 1987; see also Younger, 1985, for consistent findings obtained with schematic animal stimuli). In these studies, the facilitative effect of multiple category presentation was attributed to the fact that it provided participants with the opportunity to observe both the similarities among members within a category and the differences between members of different categories. However, there are also data indicating that when more naturalistic exemplars are used as stimuli (i.e., realistic photographs of animals), then multiple category presentation results in category representations that are either not different from or less differentiated than those formed during single-category presentation (Eimas & Quinn, 1994; Oakes, Plumert, Lansink, & Merryman, 1996; Younger & Fearing, 1999).

To explore how connectionist networks would behave under conditions of multiple category presentation, we exposed autoencoder networks identical to those in Simulation 1 to an interleaved set of cat and dog exemplars. Fifty previously untrained networks were exposed to eight cats and four dogs (the mainly cats condition), and 50 previously untrained networks were exposed to eight dogs and four cats (the mainly dogs condition). The training procedure was identical to that in Simulation 1 with one exception. As before, the networks were presented with six pairs of exemplars over six familiarization trials. Networks were trained for a fixed 250 epochs with each familiarization pair. However, on four of the six familiarization trials, one of the exemplars in the pair was taken from the contrasting category. For example, a network in the mainly dogs condition might experience the following series of familiarization pairs: cat1-dog1, dog2-dog3, dog4-cat2, cat3-dog5, dog6-dog7, dog8-cat4. In total, these networks experienced eight exemplars from the dominant category and four exemplars from the contrasting category. The trials on which an

exemplar from the contrasting category was presented were randomly selected. Networks were then tested with the remaining unfamiliar exemplars from the Cat and Dog categories, and their responses were recorded.

Figure 5 shows the networks' response to a novel cat and a novel dog after having been familiarized in either the mainly cats or the mainly dogs conditions. In contrast to the proposal that experiencing exemplars from both categories during learning might enhance the separation of the categories, these networks showed the same asymmetric exclusivity effect as those trained only with cats or only with dogs. Networks familiarized with eight cats and four dogs showed much greater error when presented with a novel dog than with a novel cat, which suggests that they formed a category of Cat that excluded dogs. The networks familiarized with eight dogs and four cats showed little difference in error when presented with novel dogs and with novel cats, which suggests that they formed a category representation that included both cats and dogs.

It could be that this asymmetry is due to the fact that the Dog category is more difficult to learn than the Cat category. However, this is not the case, because networks trained to a fixed error criterion rather than a fixed epoch criterion showed the same asymmetry. The networks trained to a fixed error criterion in the mainly cats condition had mean errors of 0.32 ( $SD = 0.02$ ) and 0.39 ( $SD = 0.02$ ) when presented with a novel cat and a novel dog, respectively. The networks trained to a fixed error criterion in the mainly dogs condition had mean errors of 0.39 ( $SD = 0.02$ ) and 0.38 ( $SD = 0.02$ ) when presented with a novel cat and a novel dog, respectively.

The persistence of the asymmetry (a) constitutes an explicit prediction of infant behaviors that derives from the associationist mechanisms of connectionist networks coupled with the characteristics of the stimuli used to familiarize infants and (b) provides a direct test of the model.

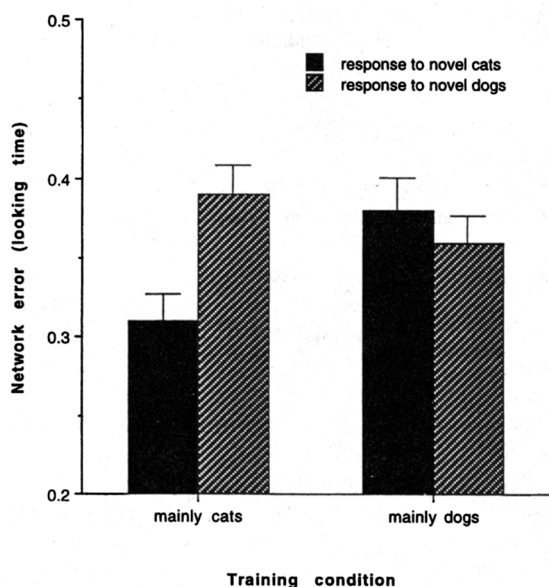


Figure 5. Mean error on a novel cat exemplar and a novel dog exemplar for networks trained with mainly cats (8 cats and 4 dogs) or mainly dogs (8 dogs and 4 cats).

## Experiment: Infant Responses to Mixed-Exemplar Familiarization

The model makes two specific predictions. The first is that 3–4-month-olds familiarized according to the procedures of the mainly cats condition will show a significant preference for novel dogs over novel cats in a subsequent preferential looking test. The second prediction is that 3–4-month-olds familiarized according to the procedures of the mainly dogs condition will show no preference for novel dogs over novel cats in a subsequent preferential looking test. We tested these predictions using the same cat and dog pictures encoded for Simulations 1 and 2.

### Method

**Participants.** Forty-eight 3–4-month-olds (27 boys and 21 girls) were participants (mean age = 103 days;  $SD = 15$  days). Nine additional infants were not included in the analyses because of fussiness ( $n = 7$ ), a position bias (>95% looking to one side of the display;  $n = 1$ ), or a failure to look at both test stimuli ( $n = 1$ ).

**Stimuli.** The stimuli were 36 color photographs of cats and dogs (18 exemplars of each category) previously used by Quinn et al. (1993) and Eimas, Quinn, and Cowan (1994). The pictures were cut from *Simon & Schuster's Guide to Cats* (Siegal, 1983) and *Simon & Schuster's Guide to Dogs* (Schuler, 1980) and were chosen to represent a variety of shapes, colors, and stances of both categories of animals. Each picture contained a single animal that had been cut away from its background and mounted onto a white posterboard ( $17.7 \times 17.7$  cm) for presentation.

**Apparatus.** Infants were tested with a portable visual preference apparatus, adapted from that used by Fagan (1970). The apparatus consists of an enclosed viewing box with a gray display stage (85 cm wide and 29 cm high) that contains two compartments to hold the two posterboard stimuli. The stimuli were illuminated by a 60-Hz fluorescent lamp that was shielded from the infant's view. The center-to-center distance between the two compartments was 30.5 cm. A 0.625-cm peephole located midway between the stimulus compartments permitted observation and recording of the infant's visual fixations.

**Procedure.** The infants were tested individually. They were brought to Paul C. Quinn's laboratory by a parent and were placed in a reclining position on the seated parent's lap. An experimenter wheeled the apparatus over the infant, keeping the infant's head centered with respect to the middle of the display stage. As soon as the infant was properly aligned and apparently at ease, a trial was begun. The experimenter loaded the stimuli from a nearby table into the stimulus compartments, elicited the infant's attention and closed the stage, thereby exposing the stimuli to the infant. The center of the display stage was approximately 30.5 cm in front of the infant while the stimuli were being viewed. During a trial, the experimenter observed the infant through the peephole and recorded fixations to the left and right stimuli using 605 XE Accusplit stopwatches, one held in each hand. The criterion for fixation was observing corneal reflection of the stimulus over the infant's pupil. Interobserver reliability—determined by comparing the looking times measured by the experimenter using the center peephole with those measured by additional observers using peepholes to the left of the left stimulus compartment and to the right of the right stimulus compartment—was high (Pearson  $r = .97$ ). This reliability was derived from observations made by independent observers on 48 novelty-preference test trials from 24 infants. This value is comparable to estimates of interobserver reliability obtained in other laboratories that measured visual fixation duration with the corneal reflection procedure (Haaf, Brewster, de Saint-Victor, & Smith, 1989; O'Neill, Jacobson, & Jacobson, 1994). Between trials, the experimenter opened the stage, recorded the looking-time data on a data sheet, changed the stimuli (or their position), recentered the infant's gaze, and closed the stage, thereby beginning the next trial. Two experimenters recorded fixations, one during

familiarization and another during test trials. Both were trained research assistants who were naive to the hypotheses of the studies. The experimenter recording during test trials was also unaware of the stimulus information that the infants were shown during the familiarization trials.

The 48 infants were randomly assigned to one of two category presentation orders. Each infant in the mainly cats group was first familiarized with eight cats and four dogs, with exemplars of the contrasting category interleaved on four separate trials. The cats and dogs were randomly selected and different for each infant and were presented during six 15-s trials (two different animals per trial). After this first familiarization phase, infants were presented with a novel cat and a novel dog for two 10-s test trials. Left-right locations were counterbalanced across infants on the first test trial and reversed on the second test trial. Infants in the mainly dogs group were familiarized and tested in the same way as those in the mainly cats group except that they saw eight dog pictures interleaved with four cat pictures.

## Results

**Familiarization trials.** Table 1 shows the mean fixation times averaged across the first three familiarization trials and the second three familiarization trials. An analysis of variance with factors of condition (mainly cats vs. mainly dogs) and trial block (1-3 vs. 4-6) revealed no significant effect of trial block on the familiarization trials,  $F(1, 46) = 0.05, p > .20$ . Neither the effect of condition nor the interaction of condition and trial block was reliable; in both cases,  $F(1, 46) < 2.50, p > .12$ . These findings suggest that any differences in the preference test outcomes cannot be attributed to category-specific differential habituation rates.

**Preference-test trials.** Each infant's looking time to the stimulus from the novel category was divided by the total looking time to both stimuli and converted to a percentage score. Mean novel-category preference scores are shown in Table 2.

The model predicts that infants familiarized in the mainly cats condition will show a significant preference for a novel dog exemplar. The model also predicts that infants familiarized in the mainly dogs condition will show no preference for the novel cat or the novel dog. Inspection of Table 2 shows that these predictions were confirmed with 3-4-month-old infants. The mean novel-category preference for novel dogs in the mainly cats condition was significantly higher than chance, whereas the mean novel-category preference for cats in the mainly dogs condition was not different from chance. In addition, the novel-category preferences for the mainly cats and mainly dogs conditions were reliably different from each other,  $t(47) = 2.08, p < .05$ , two-tailed.

In summary, these results support the model's predictions. Interleaved learning was not found to consolidate the formation of two distinct categories. The asymmetry in novelty preference for cats and dogs, identified in the original Quinn et al. (1993) studies,

Table 1  
Mean Fixation Times (in Seconds) and Standard Deviations  
During Familiarization Trials

Condition	Trials 1-3		Trials 4-6	
	<i>M</i>	<i>SD</i>	<i>M</i>	<i>SD</i>
Mainly cats	11.02	2.56	10.44	2.99
Mainly dogs	9.19	3.32	9.68	3.61

Table 2  
Mean Novel-Category Preference for the Two  
Familiarization Conditions

Measure	Familiarization condition	
	Mainly cats	Mainly dogs
Mean novel-category preference	58.32	47.73
<i>SD</i>	19.40	15.56
<i>n</i>	24	24
$t(23)$ (vs. chance)	2.10*	-0.71

\*  $p < .025$ , one-tailed.

persists even when infants are exposed to a small number of interleaved exemplars of a contrasting category during familiarization.

## General Discussion

Like young infants, connectionist autoencoder networks formed categorical representations of cats and dogs when presented with the same stimuli as the infants. The category representations showed asymmetric exclusivity. The Cat category included novel cat exemplars but excluded novel dog exemplars, whereas the Dog category included novel dog exemplars as well as novel cat exemplars. The category asymmetry was suggested to be related to the distribution of features in the stimuli shown to the infants. More specifically, the asymmetry arose because the connectionist networks developed internal representations reflecting the overlap in the distribution of the features in the two sets of stimuli. Most of the cat exemplars could be classified as dogs, whereas most dogs were not plausible cats. The asymmetric category representations reflect an interaction between the statistics of the learning environment (the images shown to the infants) and the computational properties of an associative learning system with distributed representations. Infant performance in these categorization tasks is essentially driven by a bottom-up process.

We also explored the exclusivity asymmetry by investigating whether the addition of exemplars from a contrasting category would enhance the formation of distinct Cat and Dog categories. Connectionist networks trained with eight exemplars from one category and four exemplars from a contrasting category continued to show asymmetric exclusivity in the categories developed. These results constituted a set of predictions about the behavior of 3-4-month-olds that enabled an evaluation of the model. Infants familiarized with the same mixture of cat and dog exemplars were found to show an asymmetry in their responses to novel cat and dog exemplars that was consistent with the model.

The new evidence reported in the experiment strongly supports the connectionist account of early infant categorization. The asymmetry can be explained by appealing to the associative learning mechanisms of connectionist networks and the statistical distribution of features in the stimuli used to familiarize infants. The connectionist mechanisms account for *how* the behavior emerges, and the input data account for *why* the behavior emerges in the presence of these cat and dog pictures. It could be argued that the analysis of the data alone provides the explanation of infant behaviors and that the network account contributes little to this



explanation. However, this is not the case. One can see this by trying to make predictions about how an unknown "black box" might respond to these same data. Without any information about the mechanisms that translate input into observed behaviors within the black box, it is impossible to construct an explanation of the box's behavior that will support such predictions. A full, causal understanding of behavior requires knowledge of both the information-processing mechanisms and the input data.

It is also important to understand the limitations of this model. All models are approximations. Building a model is not the same as building an infant. We do not wish to suggest that all of infant visual cognition can be accounted for with simple autoencoder networks. Nor do we wish to suggest that the infant is essentially an autoencoder. We have used the autoencoder to model looking-time behaviors because autoencoders capture the representation-construction hypothesis implicit in verbal descriptions of habituation (Charlesworth, 1969; Cohen, 1973; Sokolov, 1963). The simulation work in this article suggests that autoencoders are part of the same class of learning systems as those used by infants to learn perceptual categories (and therefore share their computational properties).

In summary, in this article we have reported on a connectionist model of infant visual categorization. Asymmetric category exclusivity was found to arise from a combination of connectionist information processing and the statistical distribution of features in the familiarization stimuli. The model predicted that asymmetric exclusivity would persist in the face of mixed-exemplar familiarization category learning. An empirical study with 3–4-month-olds confirmed the model prediction.

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## Appendix

### Measurements of Cat and Dog Stimuli

The following measurements were made from the original Quinn, Eimas, and Rosenkrantz (1993) cat and dog photographs. These data were used to train and test the networks described throughout this article.

Table A1  
*Measurements (in Millimeters) of Cat Exemplars*

Exemplar	Head length	Head width	Eye separation	Ear separation	Ear length	Nose length	Nose width	Leg length	Vertical extent	Horizontal extent
cat1	29	32	7	28	12	0	3	0	54	62
cat2	12	13	4	12	5	3	2	14	25	50
cat3	20	20	4	17	6	5	3	15	26	67
cat4	13	17	4	17	5	3	2	28	28	46
cat5	13	14	4	14	4	4	3	15	23	42
cat6	18	22	3	17	6	6	3	24	42	70
cat7	10	12	3	7	3	2	1	24	24	47
cat8	23	24	5	26	7	4	4	25	50	64
cat9	16	17	4	15	5	5	4	22	32	54
cat10	16	15	3	12	8	3	2	15	30	65
cat11	19	27	5	20	8	4	3	22	71	57
cat12	19	21	4	12	5	5	4	20	39	65
cat13	25	30	6	30	14	6	5	0	50	81
cat14	16	20	3	16	13	5	3	26	29	59
cat15	17	27	5	22	5	3	3	28	40	43
cat16	18	21	4	20	6	4	4	35	55	43
cat17	23	22	5	24	7	6	4	35	52	56
cat18	20	22	5	23	7	5	4	28	34	54

Table A2  
*Measurements (in Millimeters) of Dog Exemplars*

Exemplar	Head length	Head width	Eye separation	Ear separation	Ear length	Nose length	Nose width	Leg length	Vertical extent	Horizontal extent
dog1	16	22	0	0	16	6	7	25	21	53
dog2	23	16	0	2	8	5	8	35	21	42
dog3	16	16	4	13	5	7	6	25	26	64
dog4	20	24	4	11	7	10	10	29	22	47
dog5	15	22	4	0	20	10	6	31	34	55
dog6	13	15	3	4	8	6	4	25	19	41
dog7	15	20	3	5	9	8	5	28	26	60
dog8	13	9	4	12	8	7	5	19	20	49
dog9	15	21	3	10	19	3	3	32	20	46
dog10	33	30	11	37	12	3	4	40	50	66
dog11	17	17	5	13	6	7	5	28	22	55
dog12	29	21	6	31	15	15	13	31	28	58
dog13	19	15	6	20	19	10	9	34	46	44
dog14	25	20	6	28	15	10	8	28	30	55
dog15	21	24	7	0	15	10	8	20	32	49
dog16	23	20	7	23	15	8	6	26	34	36
dog17	16	21	6	0	10	7	10	28	21	62
dog18	14	22	3	0	15	9	6	24	26	30

Received December 22, 1998  
Revision received April 14, 2000  
Accepted April 14, 2000 ■